

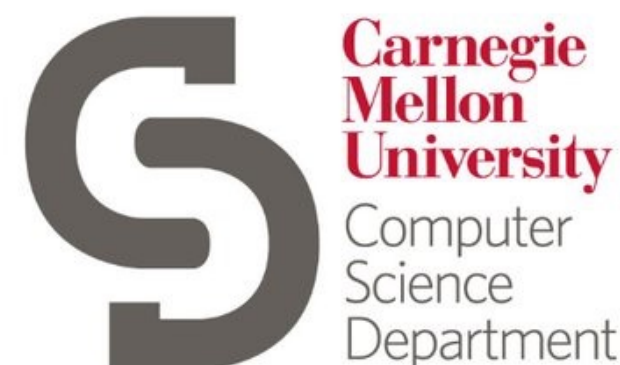
Parallel Complexity Analysis with Temporal Session Types

Ankush Das

Jan Hoffmann

Frank Pfenning

ICFP, Sep 26, 2018



What is Parallel Complexity? ²



a.k.a. Span

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a.k.a. Span

Total time of computation?

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Total time of computation?

Depends on amount of parallelism in system

What is Parallel Complexity? ²



a.k.a. Span

Total time of computation?

Depends on amount of parallelism in system

**Data
Dependencies**

**Wait for
Messages**

**Data Races
Shared Memory**

Why Parallel Complexity?

Why Parallel Complexity?

3



Complexity of Parallel Algorithms

Blelloch (Comm. ACM '96)

Why Parallel Complexity?

3



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Design of Optimal Scheduling Policies

Acar et. al. (JFP '16)

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Throughput and Latency of Streams

Mamouras et. al. (PLDI '17)

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Complexity of Parallel Algorithms

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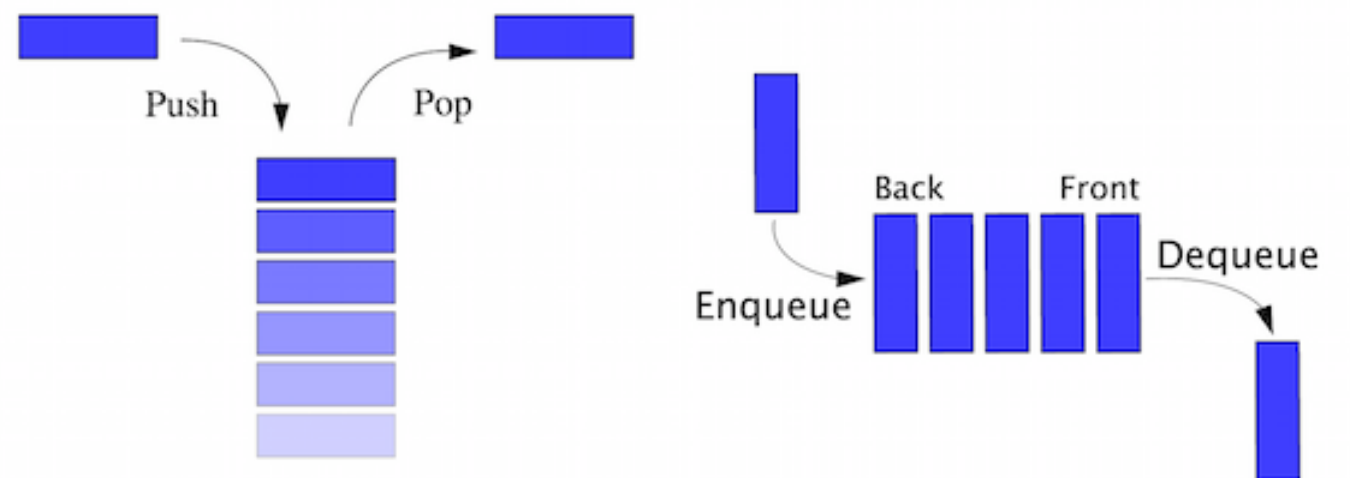
Throughput and Latency of Streams

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Design of Optimal Scheduling Policies

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Response Time of Concurrent Data Structures

Ellen and Brown (PODC '16)

Why Session Types?

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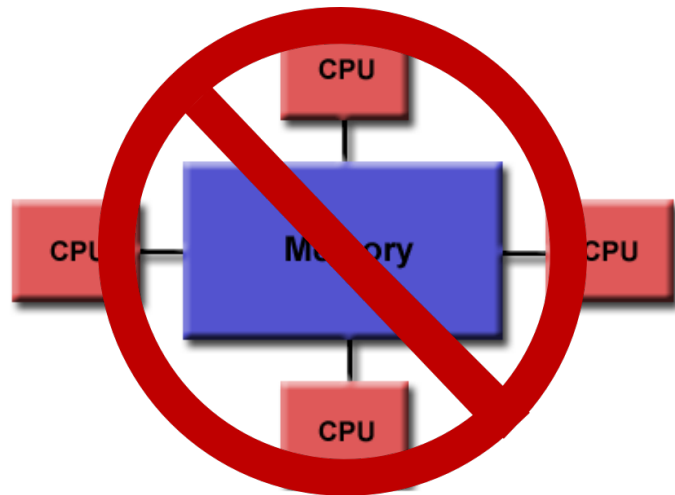
4

Concurrent Programs are hard to analyze!

Why Session Types?

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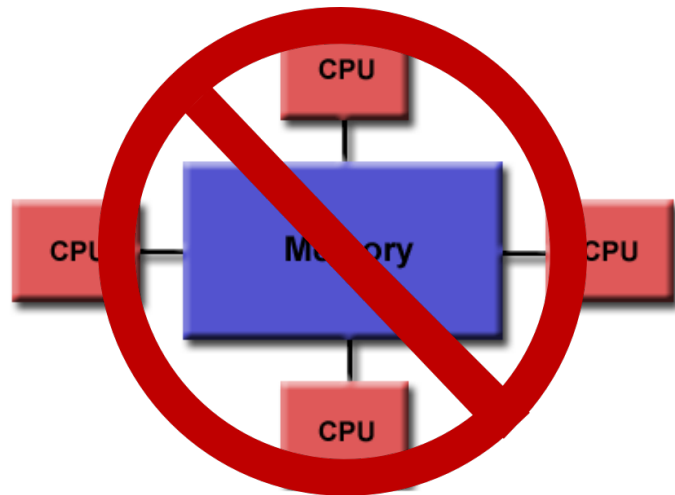


No Shared Memory

Why Session Types?

4

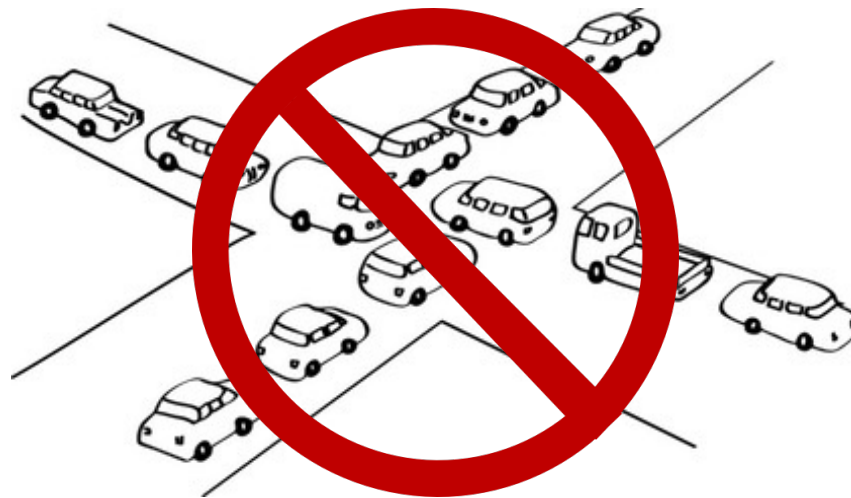
Concurrent Programs are hard to analyze!



No Shared Memory



Types strictly enforce communication protocols



Deadlock Freedom

What are Session Types?

5

- ▶ **Implement message-passing concurrent programs**
- ▶ **Communication via typed bi-directional channels**
- ▶ **Curry-Howard isomorphism with intuitionistic linear logic**

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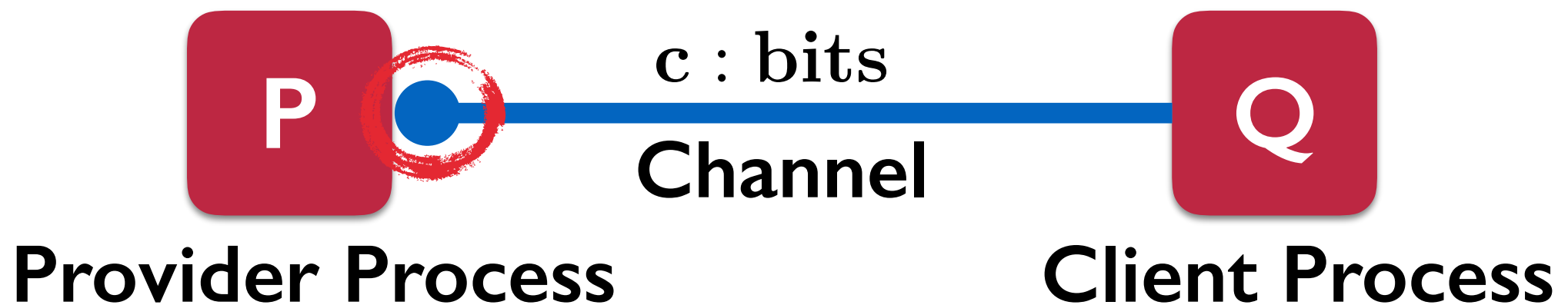


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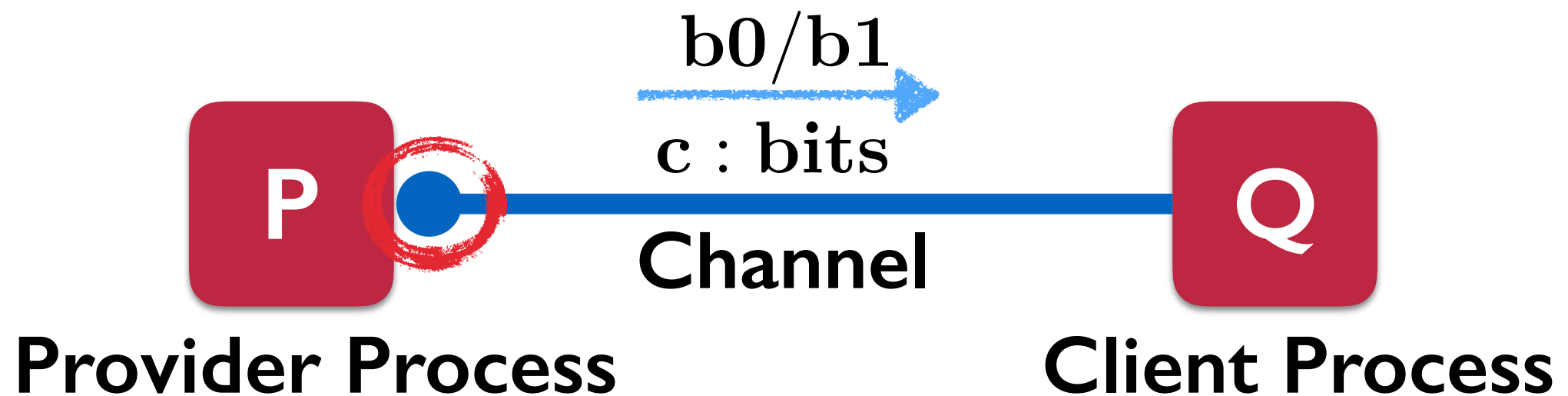


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Contributions

Type system to analyze timings of message exchanges of session-typed programs

Type system to analyze timings of message exchanges of session-typed programs

- ▶ types define the *timing* of message exchanges
- ▶ provides *precision* and *flexibility*
- ▶ proved *sound* w.r.t. *cost semantics* tracking time
- ▶ *conservative* extension to typical session type system
- ▶ applies to all *standard* session types examples
- ▶ can be *parameterized* to count resource of interest

How is time defined?

7

- ▶ Time is defined using a cost model
- ▶ *Cost model* assigns a time cost to each operation

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\mathcal{R} cost model
Unit delay after
each receive

\mathcal{RS} cost model
Unit delay after each
receive and send

How is time defined?

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- ▶ *Cost model* assigns a time cost to each operation

\mathcal{R} cost model

Unit delay after
each receive

\mathcal{RS} cost model

Unit delay after each
receive and send

- ▶ Expressed by inserting appropriate delays in the source code, only the delays cost time
- ▶ Programmer specifies cost model, compiler automatically inserts delays for type checking

$$\Omega \vdash P :: (x : S)$$

Definition of the Types

Track Message Rates

9



Track Message Rates

9



Compute output rate given input rate

Track Message Rates

9



Compute output rate given input rate

timing of messages \Leftrightarrow Parallel Complexity

Track Message Rates

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Compute output rate given input rate

timing of messages \Leftrightarrow Parallel Complexity

Necessary:

need exact input/
output rate to ensure
compositionality

Sufficient:

span can be thought as
timing of final message

Example: Bit Streams

10

$$\text{bits} = \oplus \{b0 : \text{bits}, b1 : \text{bits}, \$: 1\}$$

- $\vdash \text{two} :: (\text{c} : \text{bits})$

Example: Bit Streams

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$$\text{bits} = \oplus \{b0 : \text{bits}, b1 : \text{bits}, \$: 1\}$$

• $\vdash \text{two} :: (\text{c} : \text{bits})$

```
c ← two =  
  c.b0 ;  
  c.b1 ;  
  c.$  ;  
  close c
```

$\text{c} : \text{bits}$



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$\text{c} \leftarrow \text{two} =$

$\frac{\text{c.b0} ;}{\text{c.b1} ;}$

$\text{c.\$} ;$

close c

$\text{c} : \text{bits}$

$b0$

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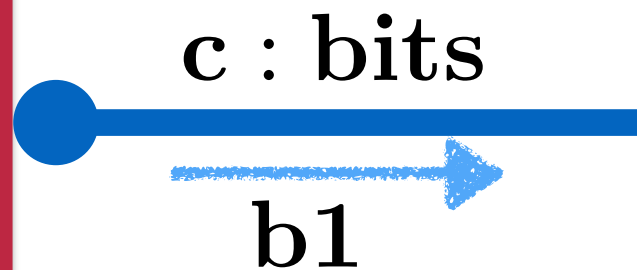
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b1

b0

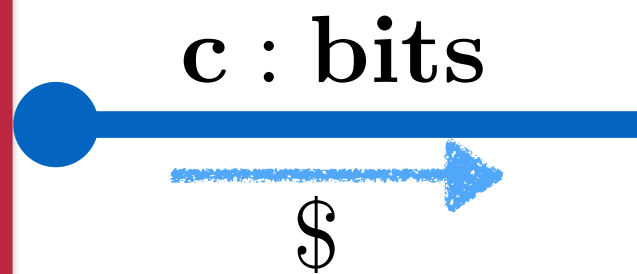
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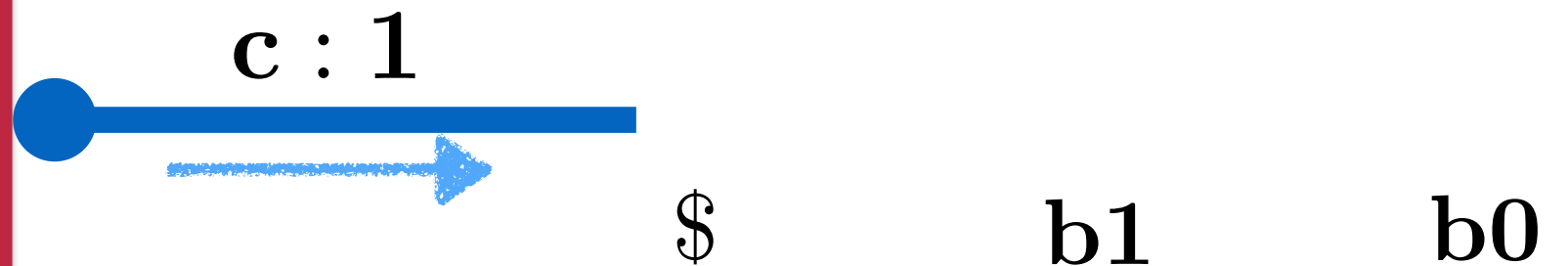
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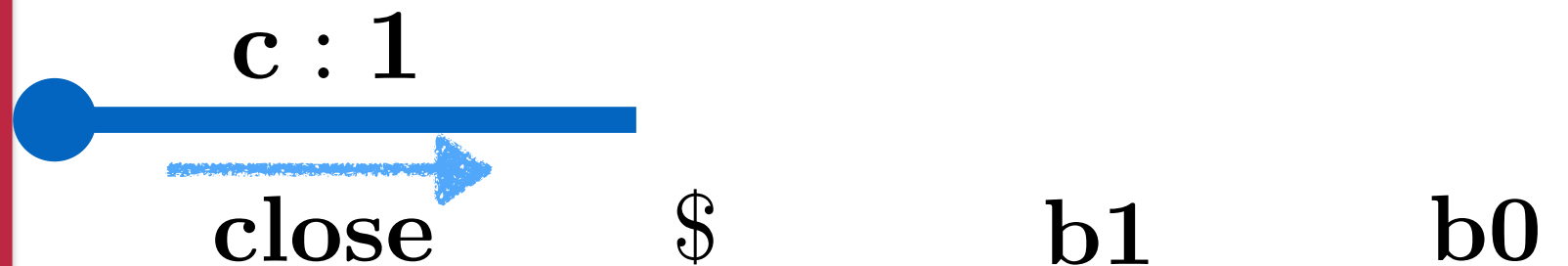
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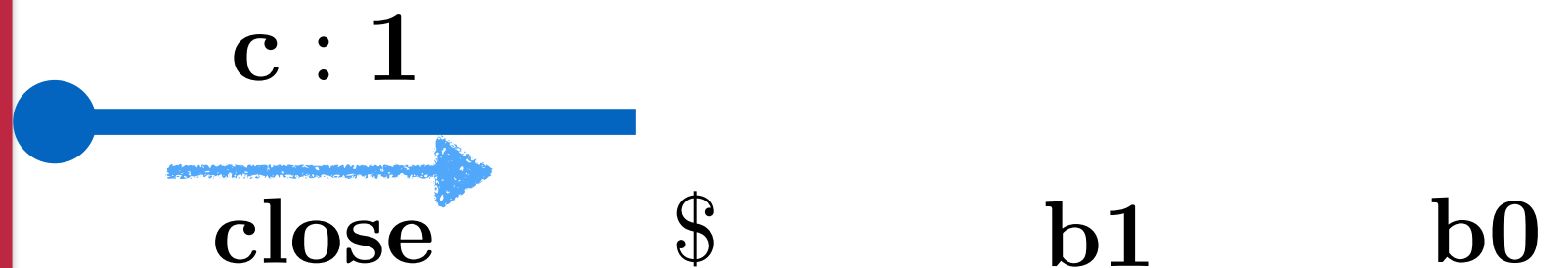
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Timing Information?

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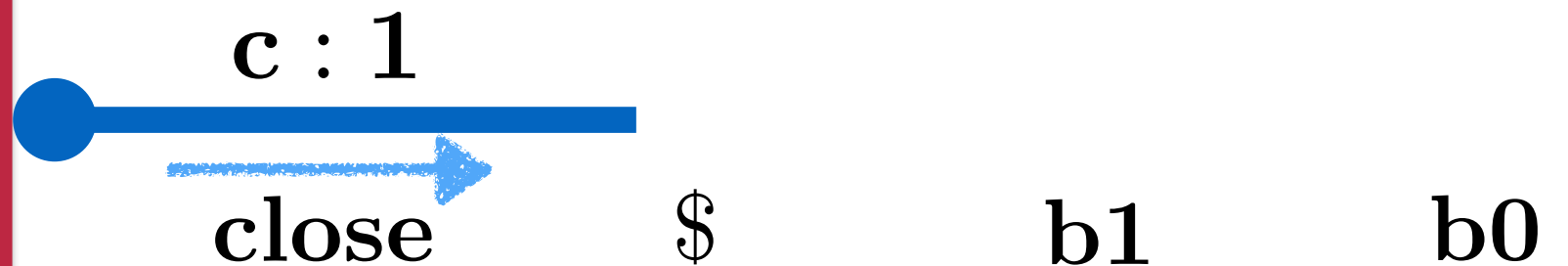
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Timing Information?

Sending a message
causes unit delay

Example: Bit Streams

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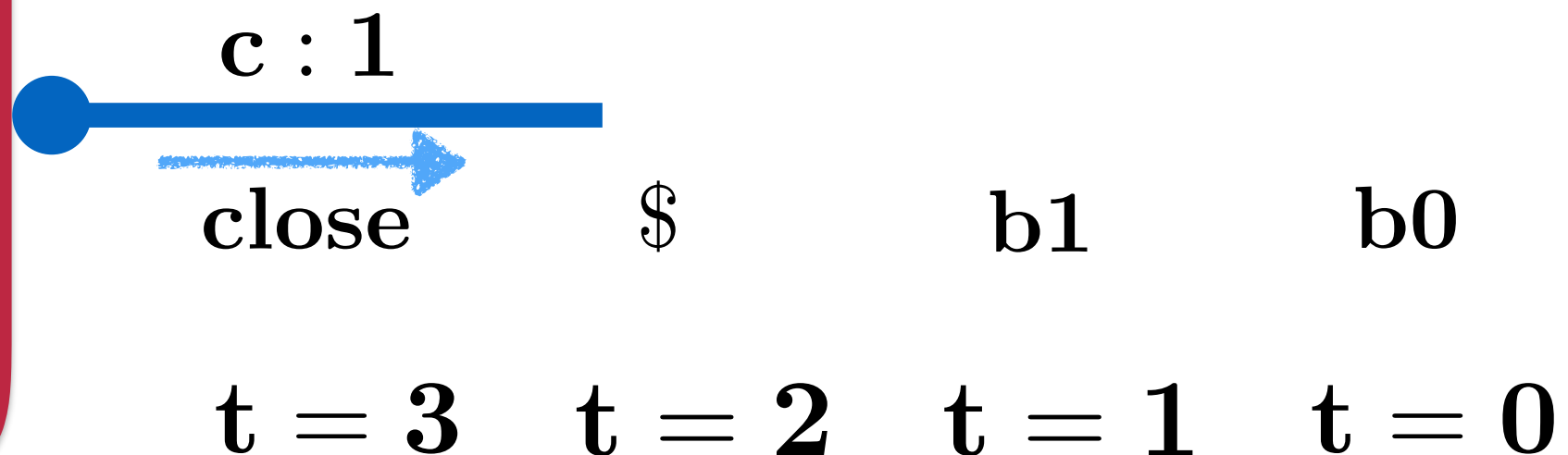
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Timing Information?

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Enforcing Time in the Type ¹¹

$$\mathbf{bits} = \oplus \{ \mathbf{b0} : \bigcirc \mathbf{bits}, \mathbf{b1} : \bigcirc \mathbf{bits}, \$: \bigcirc \mathbf{1} \}$$

Enforcing Time in the Type ¹¹

$\text{bits} = \oplus \{ \mathbf{b0} : \bigcirc \text{bits}, \mathbf{b1} : \bigcirc \text{bits}, \$: \bigcirc 1 \}$

Next Operator - expresses unit delay

Three blue arrows originate from the text box and point to the three occurrences of the Next Operator (represented by a circle with a dot) in the type signature above: one pointing to the one in $\bigcirc \text{bits}$ for $\mathbf{b0}$, one pointing to the one in $\bigcirc \text{bits}$ for $\mathbf{b1}$, and one pointing to the one in $\bigcirc 1$ for $\$$.

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Next Operator - expresses unit delay

• $\vdash \mathbf{two} :: (\mathbf{c} : \text{bits})$

```
c ← two =  
c.b0 ; delay ;  
c.b1 ; delay ;  
c.$  ; delay ;  
close c
```

$\mathbf{c} : \text{bits}$

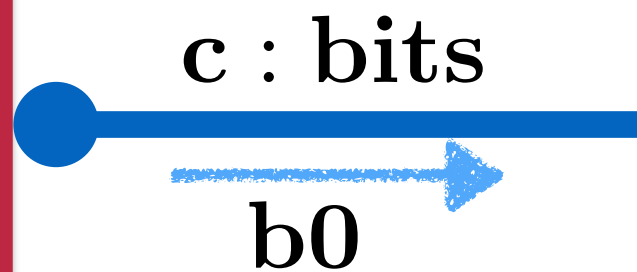
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$t = 0$

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b0

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$\mathbf{b0}$

$t = 1 \quad t = 0$

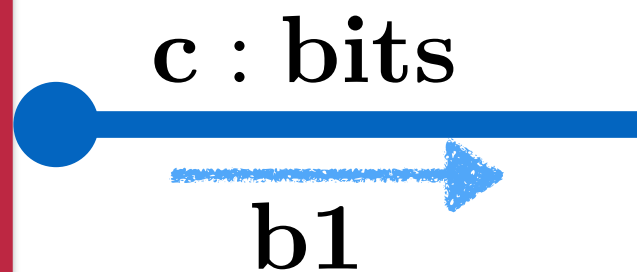
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b1	b0
$t = 1$	$t = 0$

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	$\mathbf{b1}$	$\mathbf{b0}$
$t = 2$	$t = 1$	$t = 0$

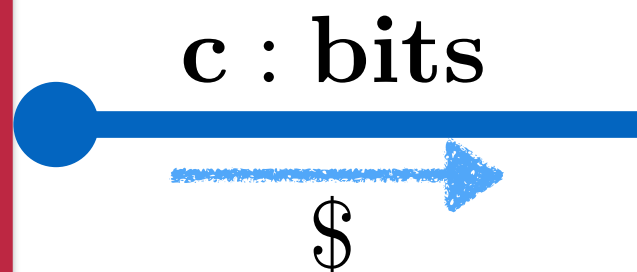
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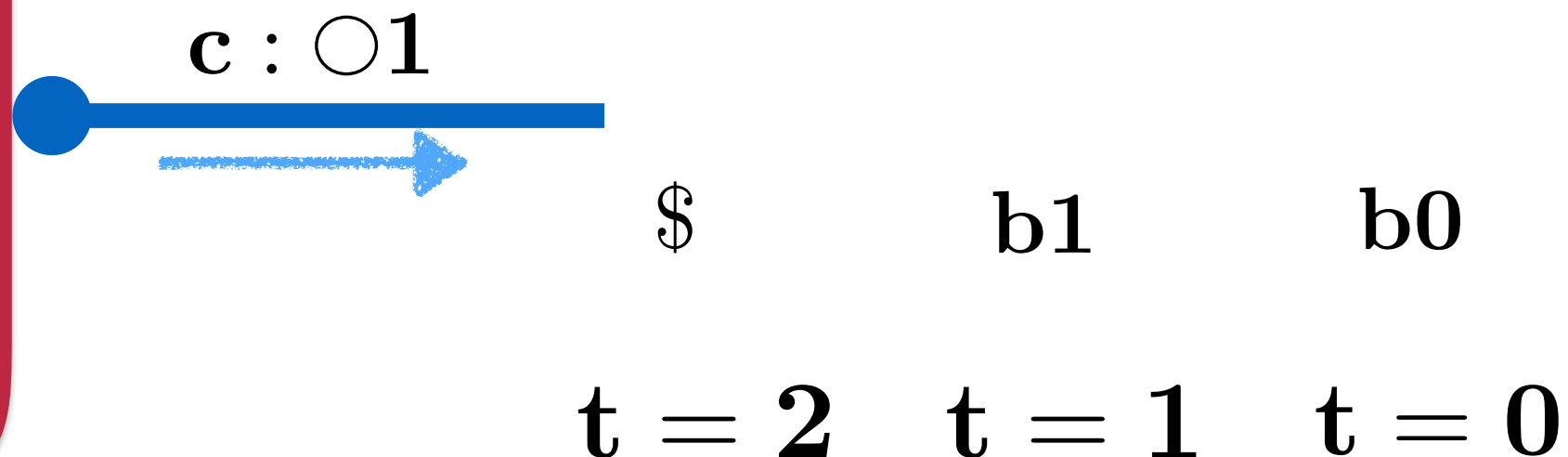
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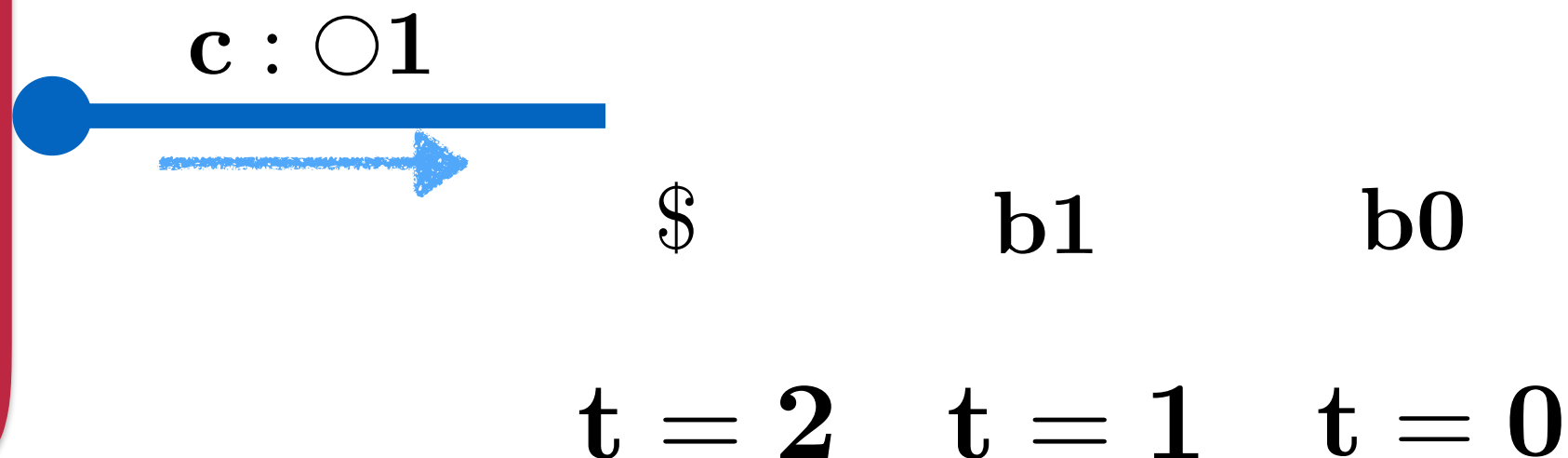
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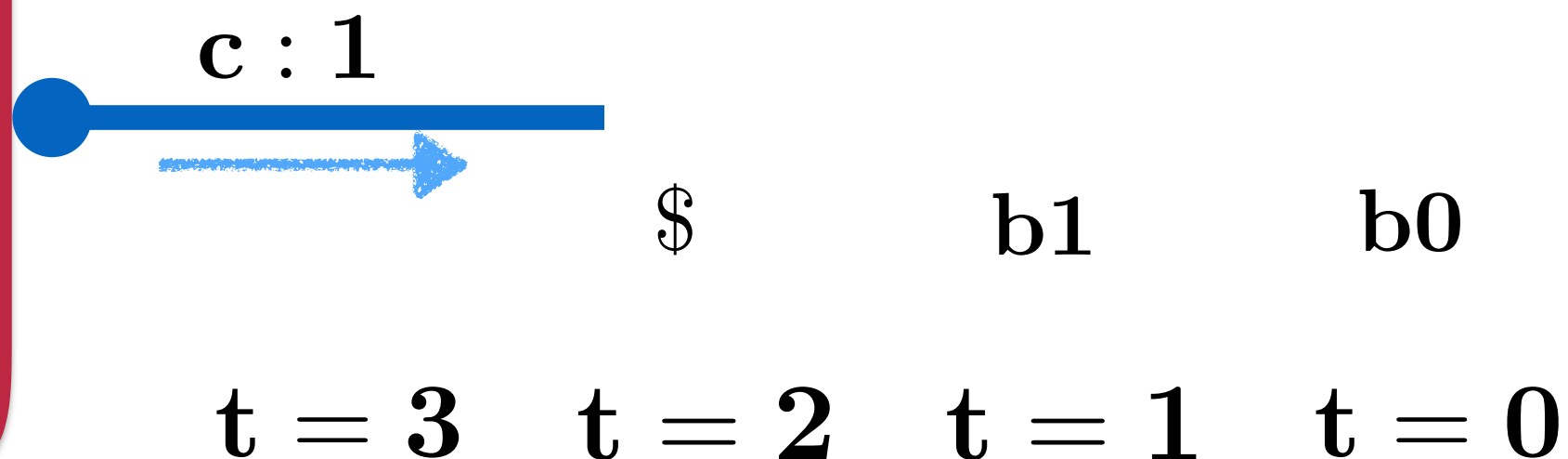
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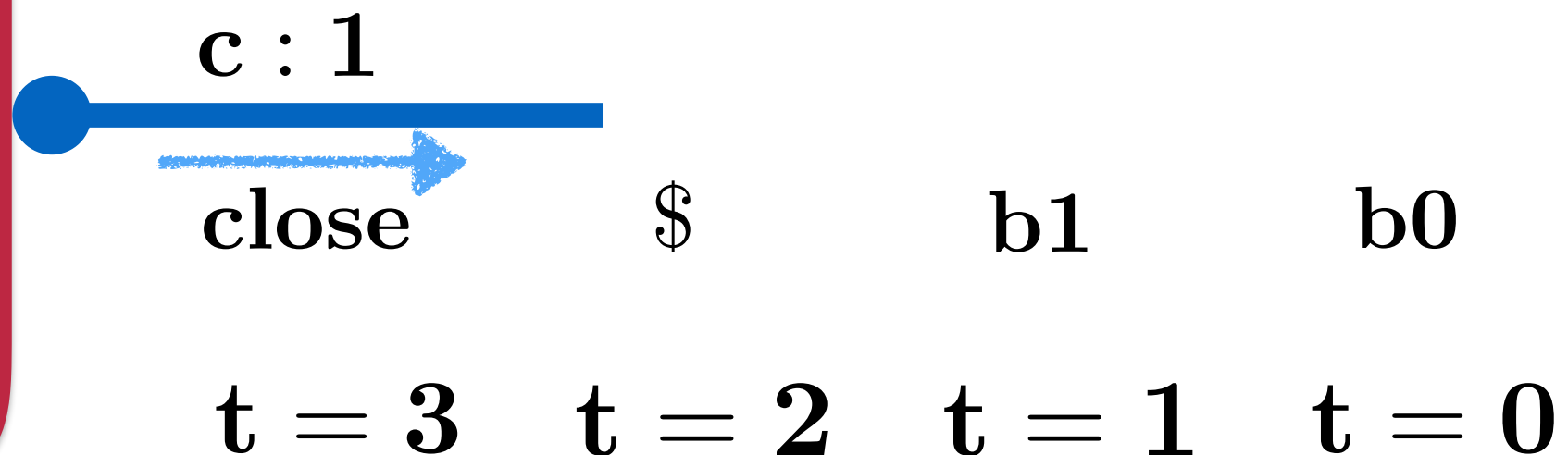
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 $\mathbf{c.\$} ; \text{delay} ;$
 $\text{close } \mathbf{c}$



Typing Rule (\odot)

12

applied
pointwise

$$\frac{\Omega \vdash P :: (x : S)}{\odot \Omega \vdash \text{delay}; P :: (x : \odot S)}$$

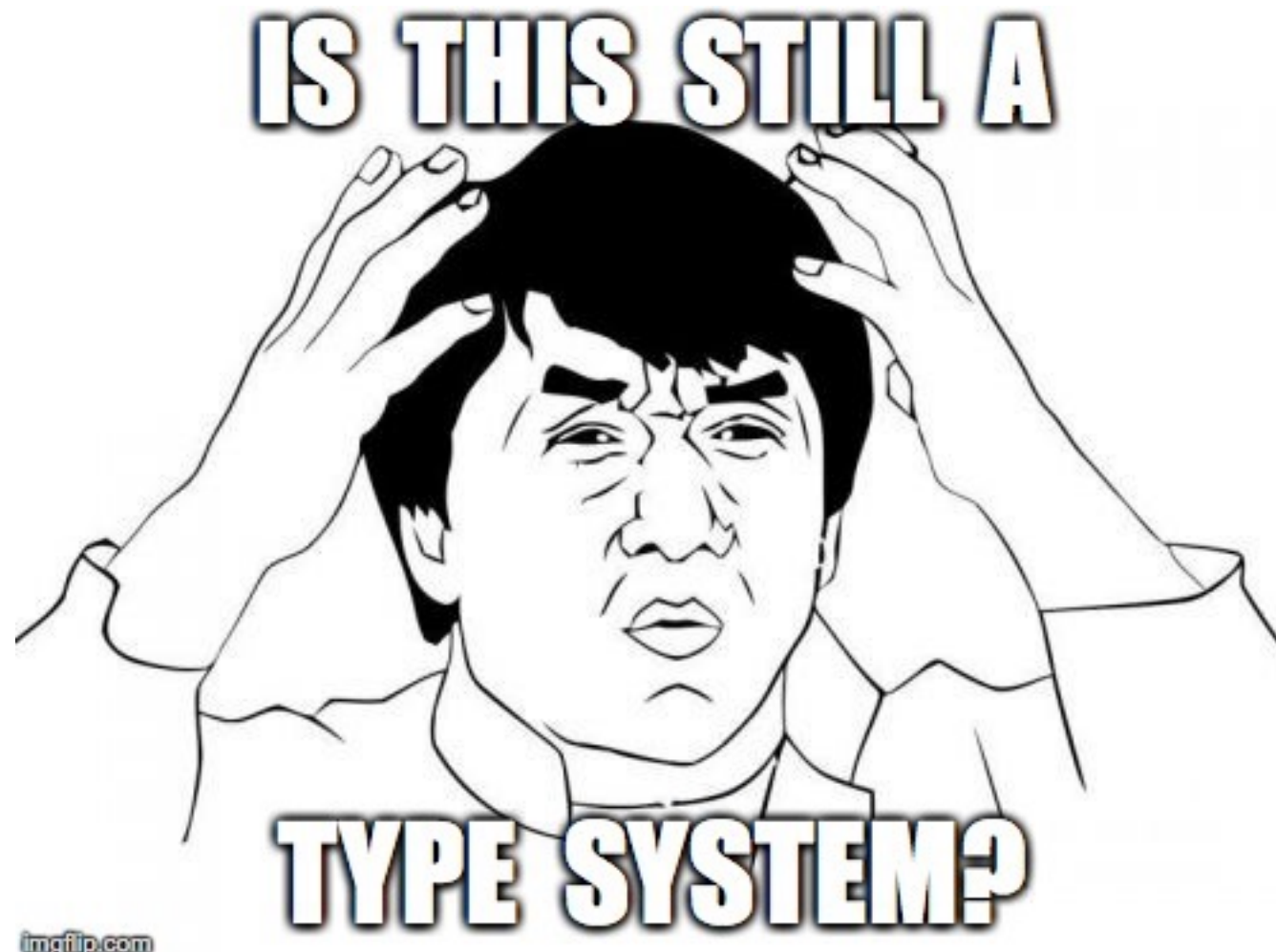
Typing Rule (\bigcirc)

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applied
pointwise

$$\frac{\Omega \vdash P :: (x : S)}{\bigcirc\Omega \vdash \text{delay}; P :: (x : \bigcirc S)}$$

breaks the locality property of type system!



Bit Streams

13

\mathcal{R} cost model

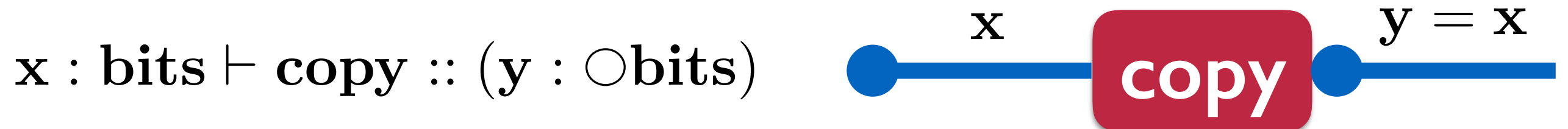
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Bit Streams

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Bit Streams

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$$\text{bits} = \oplus \{ \mathbf{b0} : \bigcirc^r \text{bits}, \mathbf{b1} : \bigcirc^r \text{bits}, \$: \bigcirc^r \mathbf{1} \}$$

$x : \text{bits} \vdash \text{copy} :: (y : \bigcirc \text{bits})$



$x : \text{bits} \vdash \text{plus1} :: (y : \bigcirc \text{bits})$

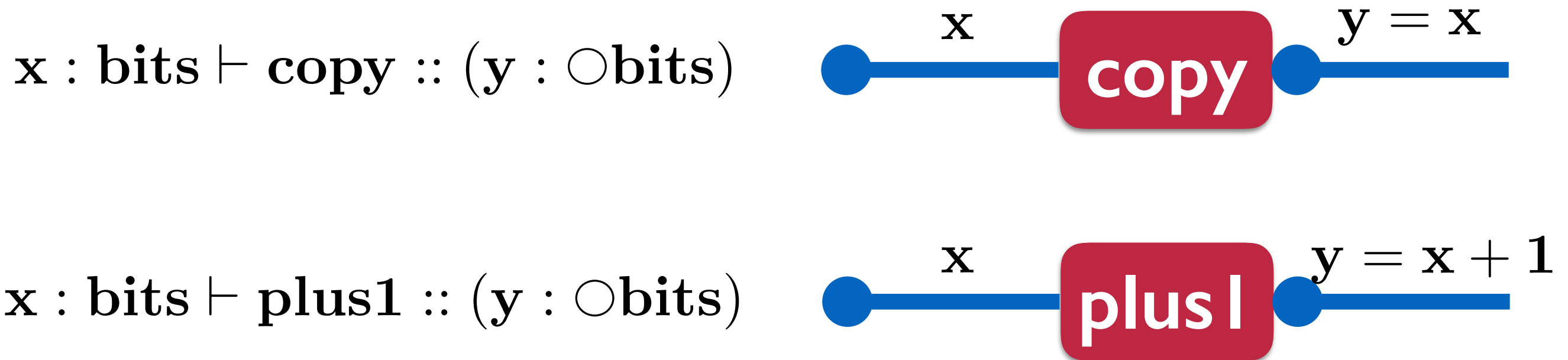


Bit Streams

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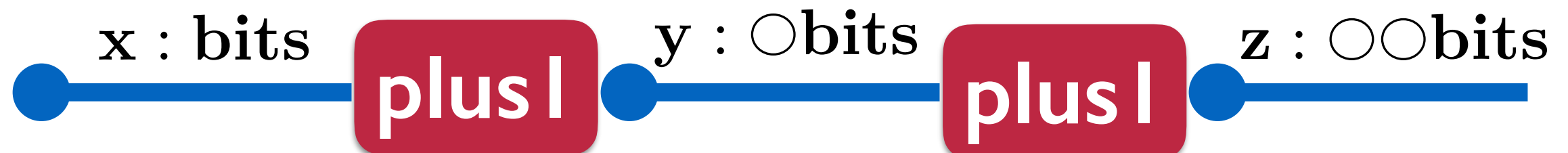
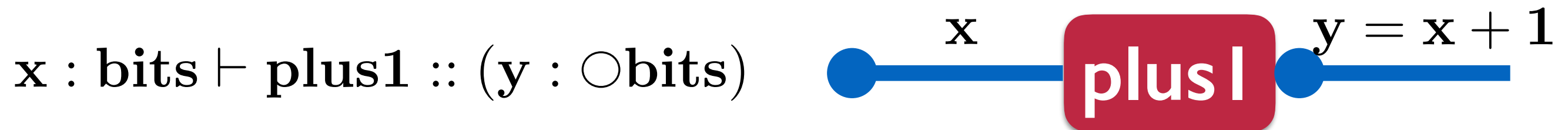
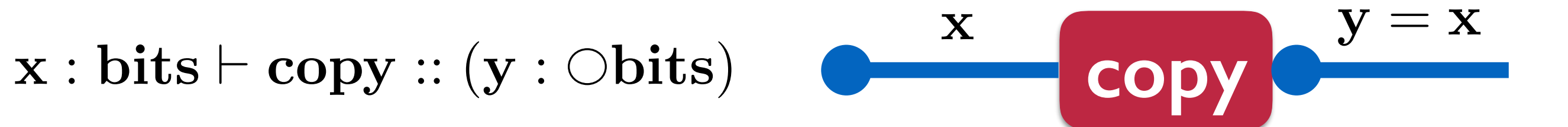


Bit Streams

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$$x : \text{bits} \vdash \text{plus2} :: (z : \bigcirc \bigcirc \text{bits})$$

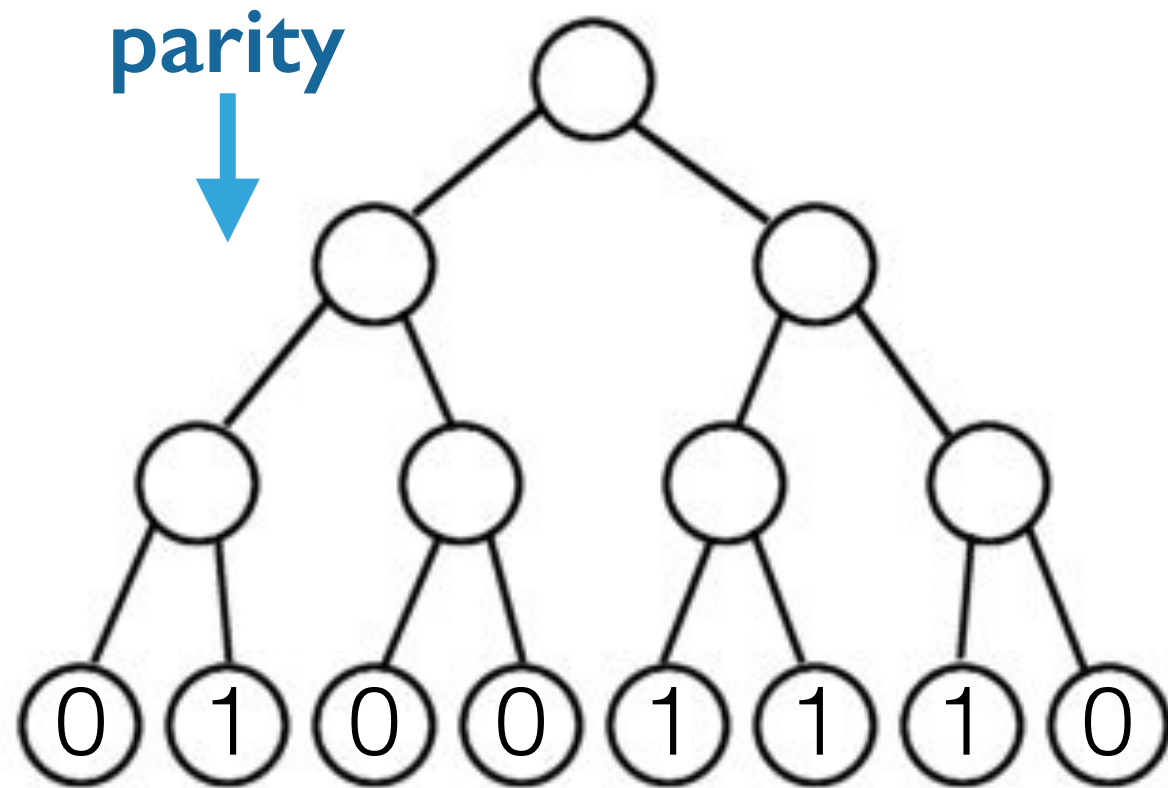
14



Compute the parity

Fork-Join Parallelism

14

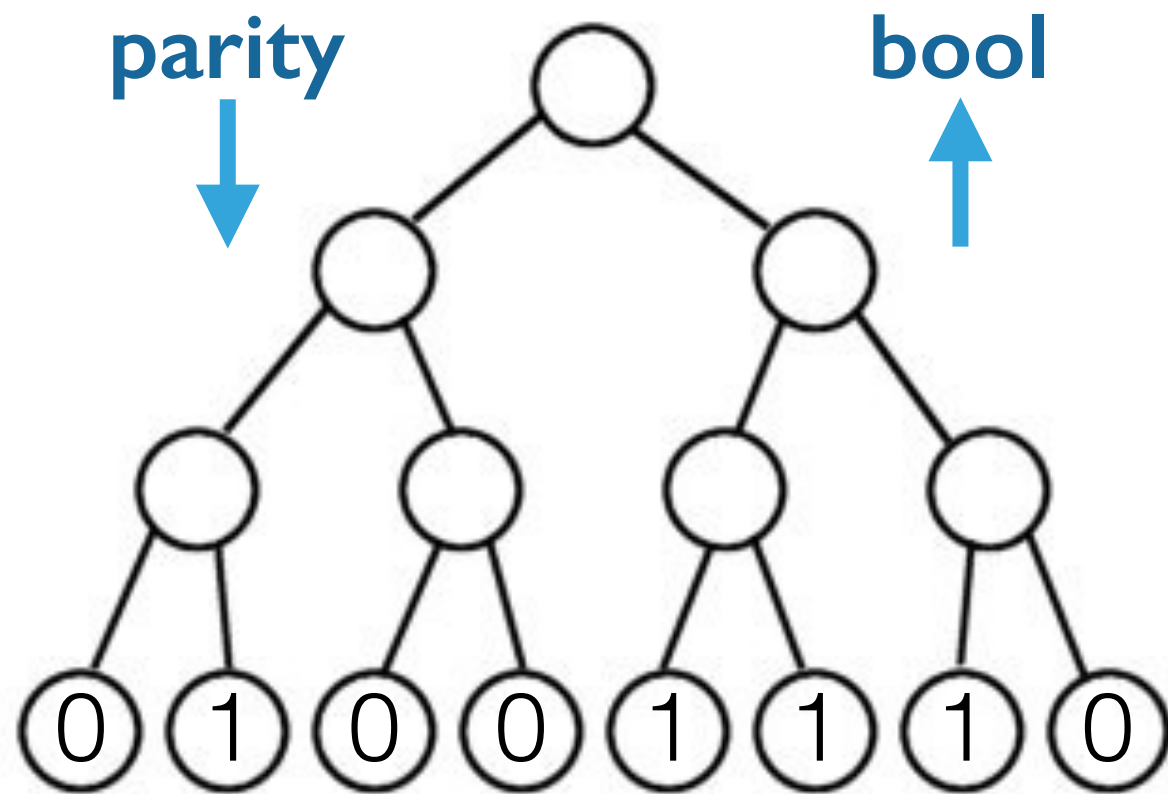


0s and 1s at the leaves

Compute the parity

Fork-Join Parallelism

14

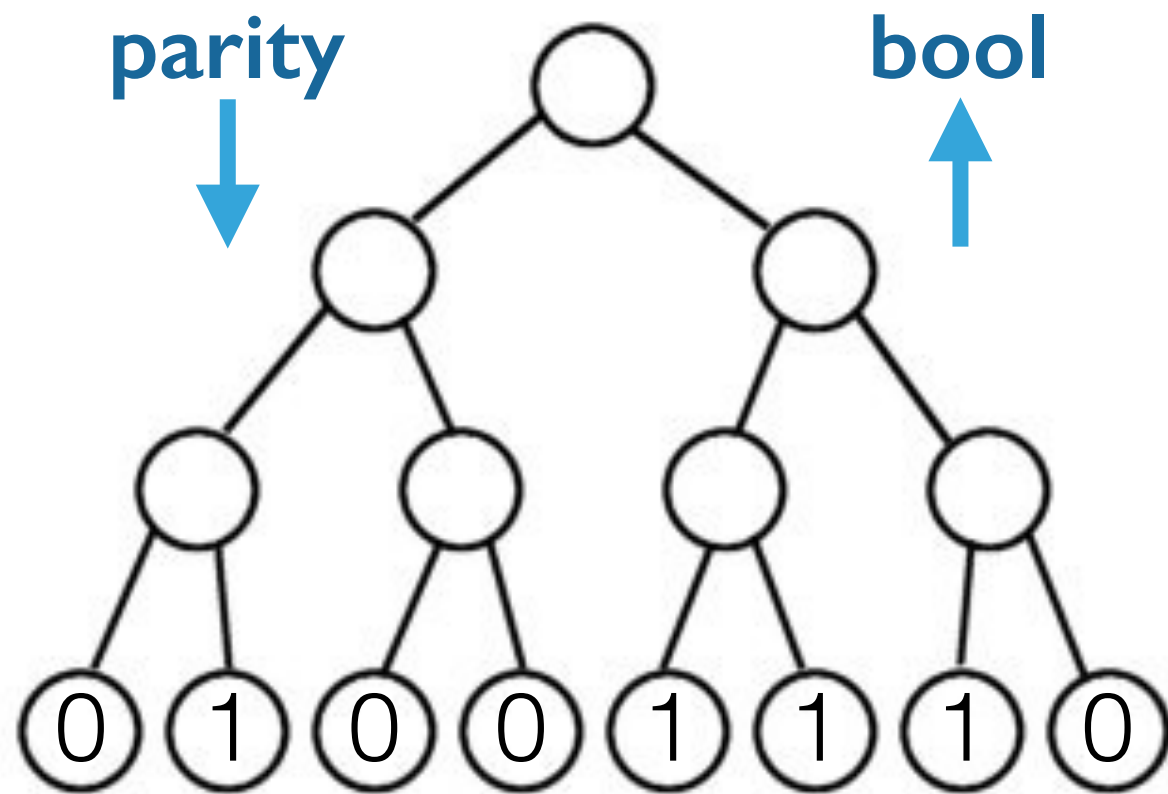


0s and 1s at the leaves

Compute the parity

Fork-Join Parallelism

14



0s and 1s at the leaves

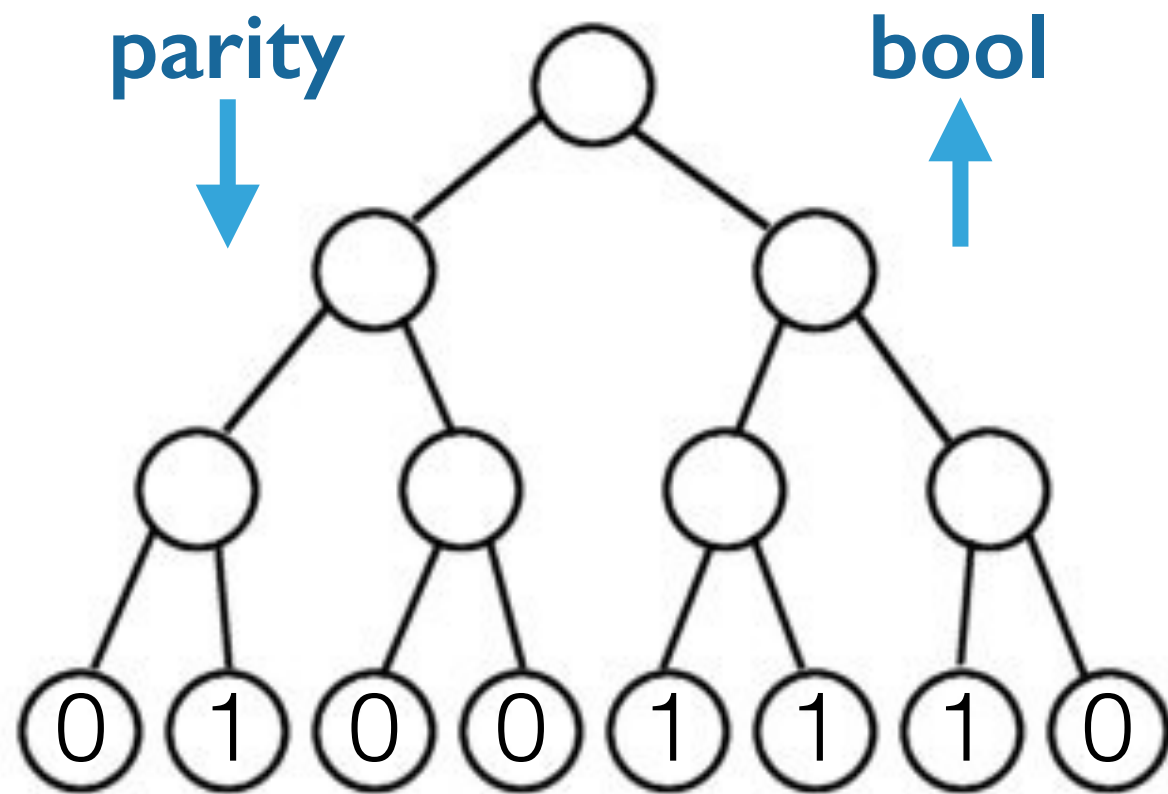
Compute the parity

RS **cost model**

$$\text{tree}[h] = \&\{\text{parity} : \bigcirc^{5h+3}\text{bool}\}$$

Fork-Join Parallelism

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0s and 1s at the leaves

Compute the parity

\mathcal{RS} cost model

$$\text{tree}[h] = \&\{\text{parity} : \bigcirc^{5h+3}\text{bool}\}$$

Counting xors

$$\text{tree}[h] = \&\{\text{parity} : \bigcirc^h\text{bool}\}$$

Can we type the queue?

15



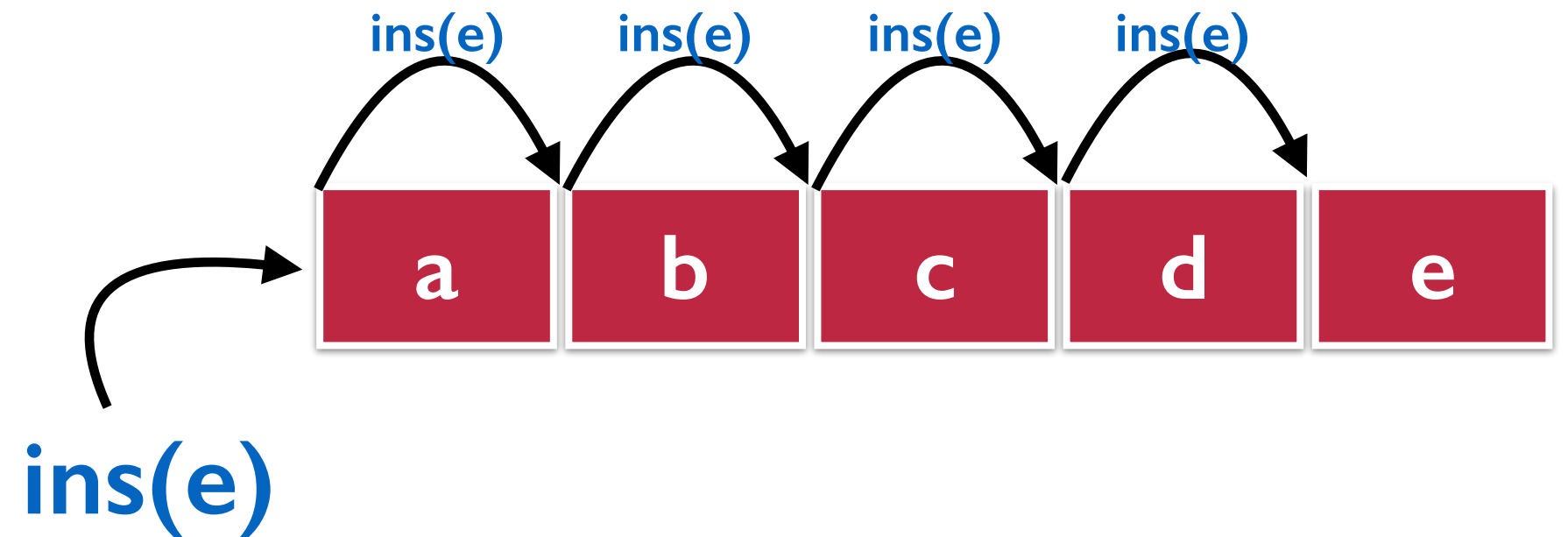
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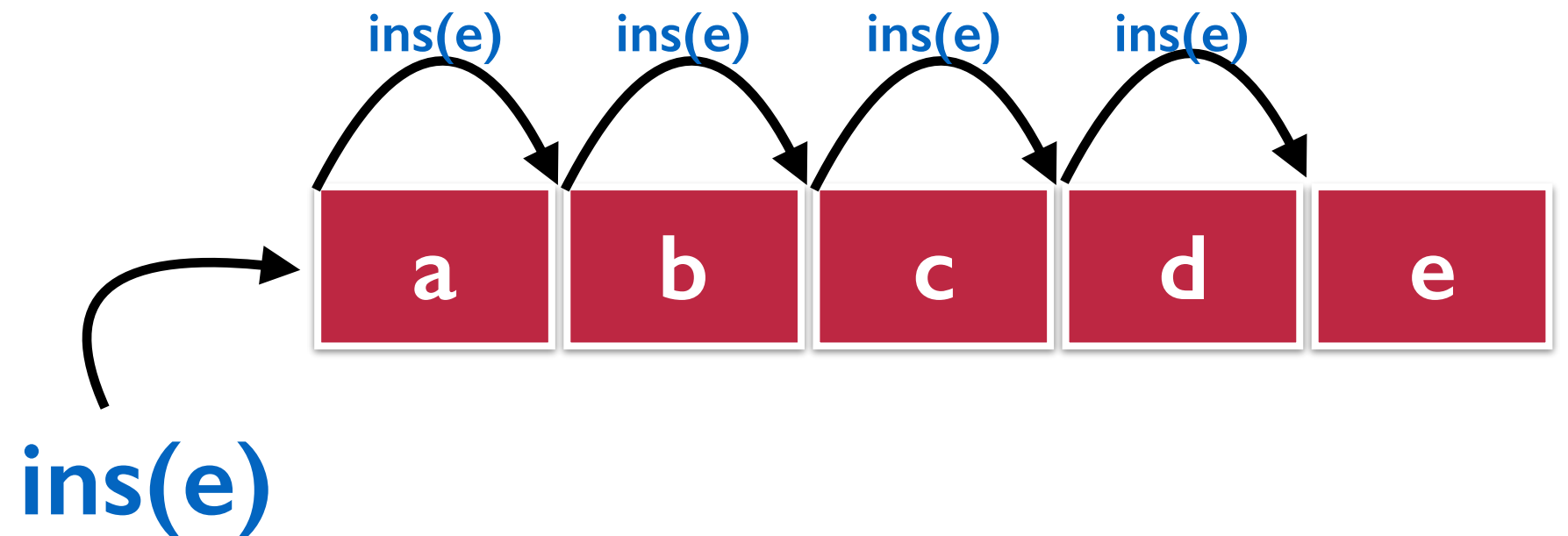
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Can we type the queue?

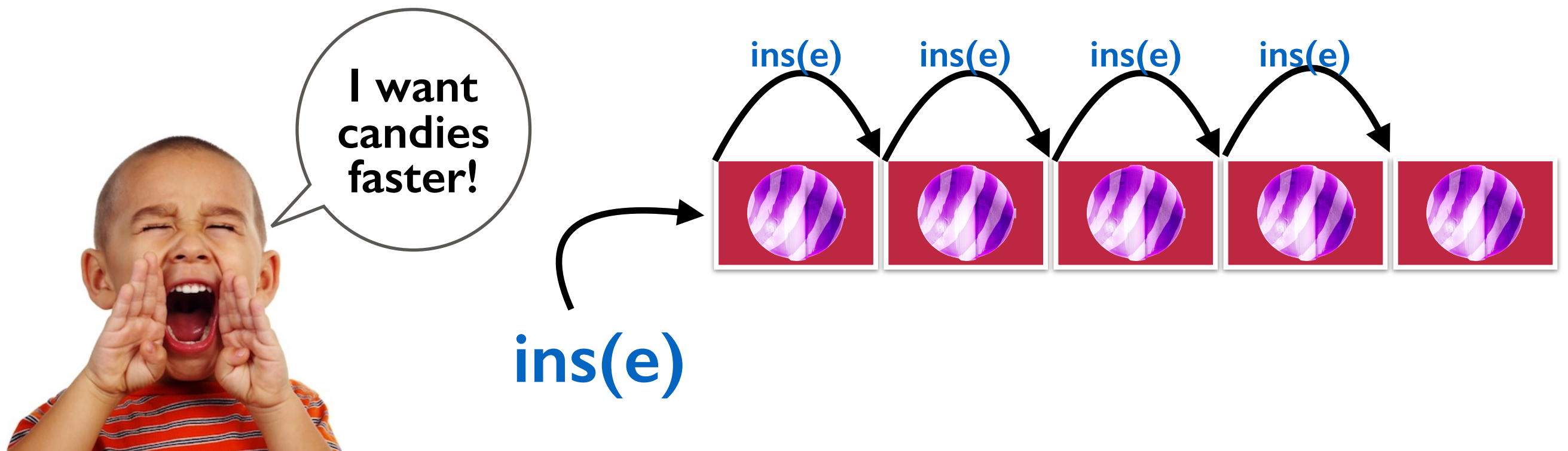
15



- ▶ Next operator only expresses constant insertion rate
- ▶ But rate of insertion at the tail depends on the size of the queue — longer the queue, slower the rate
- ▶ To maintain a constant rate at the tail, new elements must be inserted at a faster rate than the previous one

Can we type the queue?

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**The Next Operator
is too precise!**

**Adding Flexibility
to the Type System**

- ▶ **The Box Operator (\square)**
 - ▶ Provider Action: always be ready to receive token
 - ▶ Client Action: eventually send the token
 - ▶ Provider doesn't know when the token will come, only the client does
 - ▶ Different from \bigcirc operator where both provider and client knew the timing of message exchange
- ▶ **The Diamond Operator (\diamond)**
 - ▶ Dual of the Box operator (provider and client flip)

Typing the Queue

18



$$\begin{aligned} \text{queue}_{\mathbf{A}} = & \&\{\text{ins} : \mathbf{A} \multimap \text{queue}_{\mathbf{A}}, \\ & \text{del} : \oplus\{\text{none} : 1, \\ & \quad \text{some} : \mathbf{A} \otimes \text{queue}_{\mathbf{A}}\}\} \end{aligned}$$

Typing the Queue

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offers choice
of ins/del

$\text{queue}_A = \&\{\text{ins} : A \multimap \text{queue}_A,$

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Typing the Queue

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offers choice
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recv element
of type A

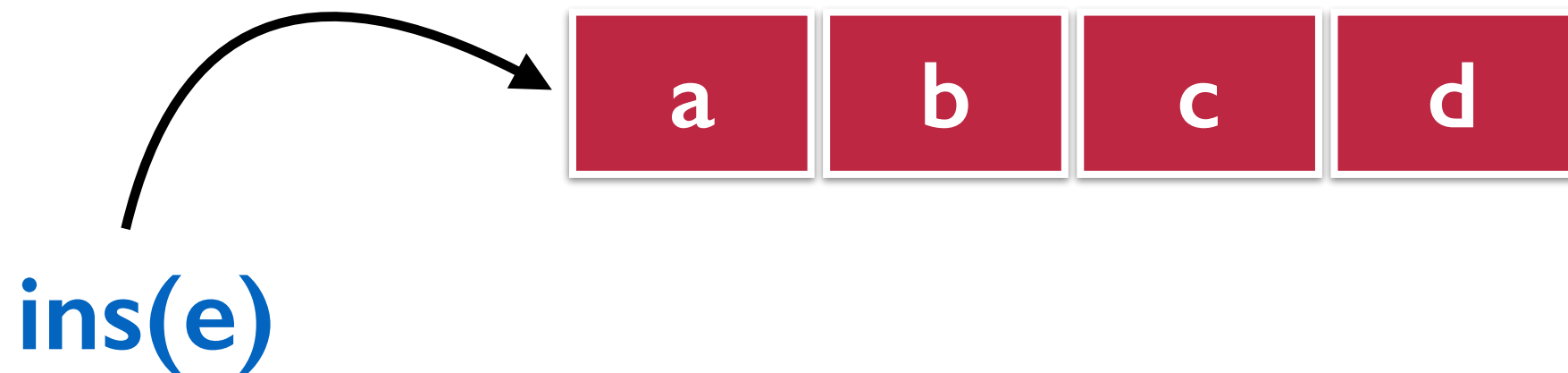
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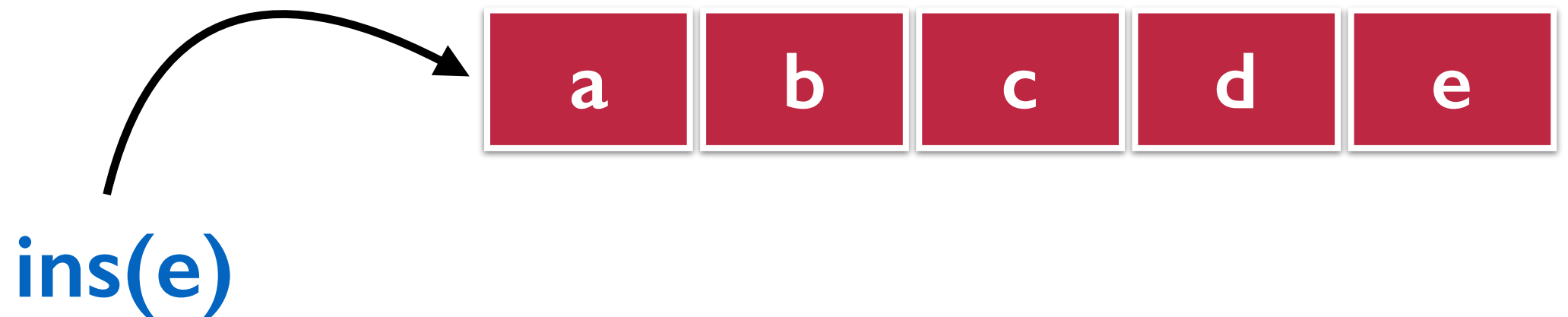
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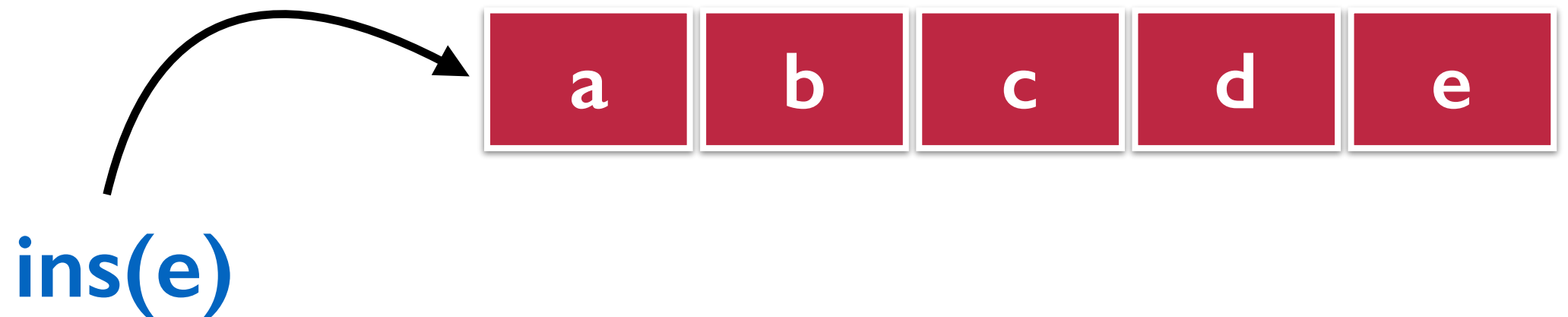
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Typing the Queue

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offers choice
of ins/del

recv element
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behave as
queue again

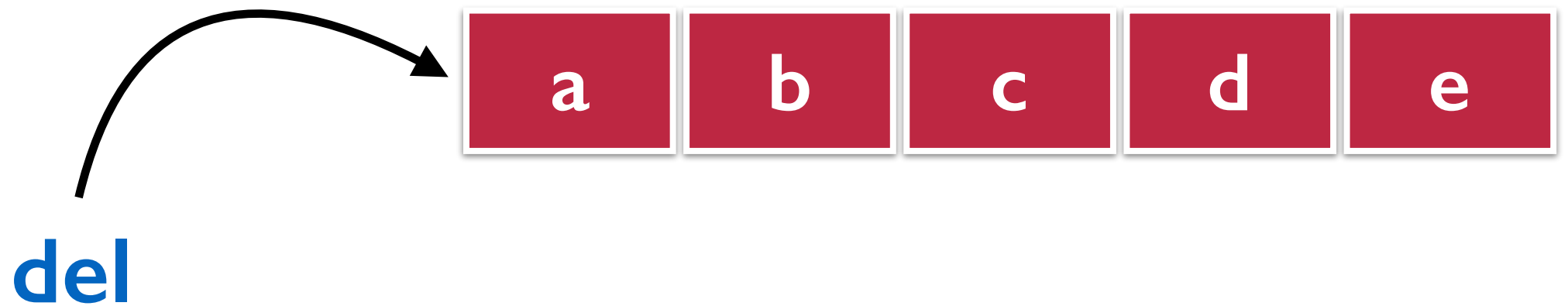
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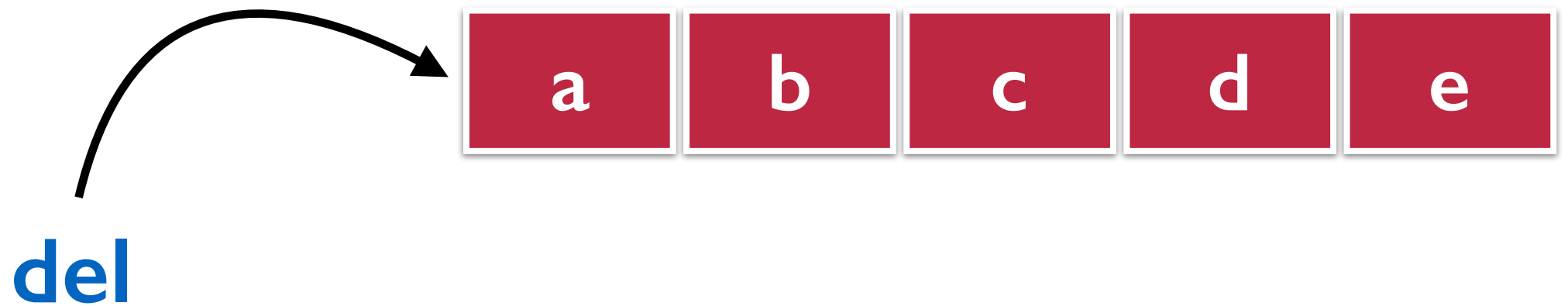
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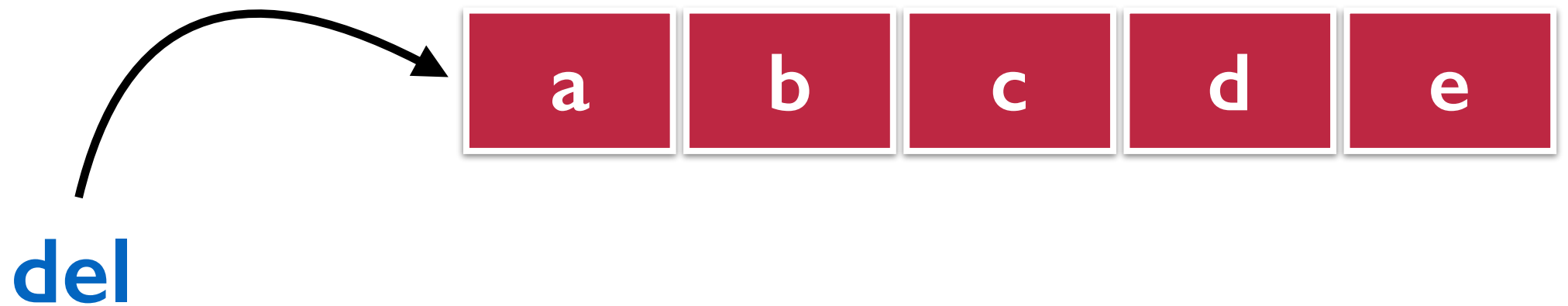
$\text{del} : \oplus\{\text{none} : 1,$

send none if
queue is empty

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Typing the Queue

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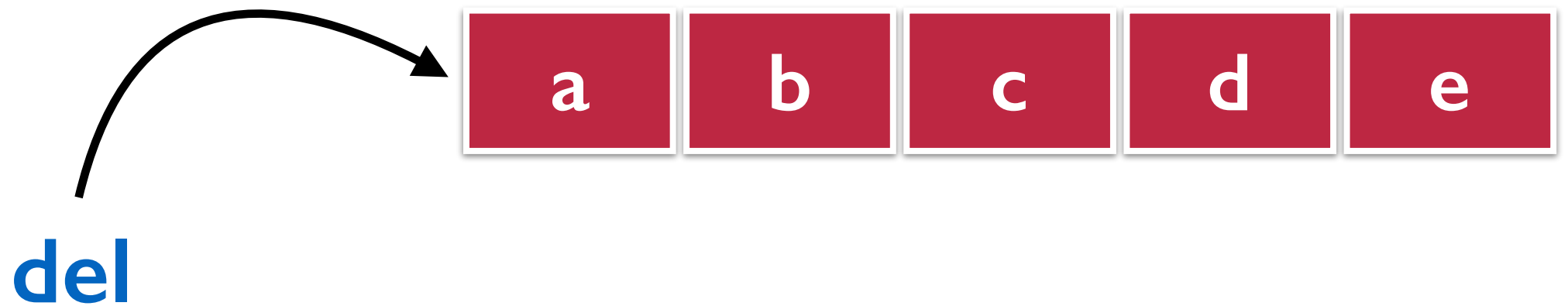
$\text{some} : A \otimes \text{queue}_A\}\}$

terminate

send none if
queue is empty

Typing the Queue

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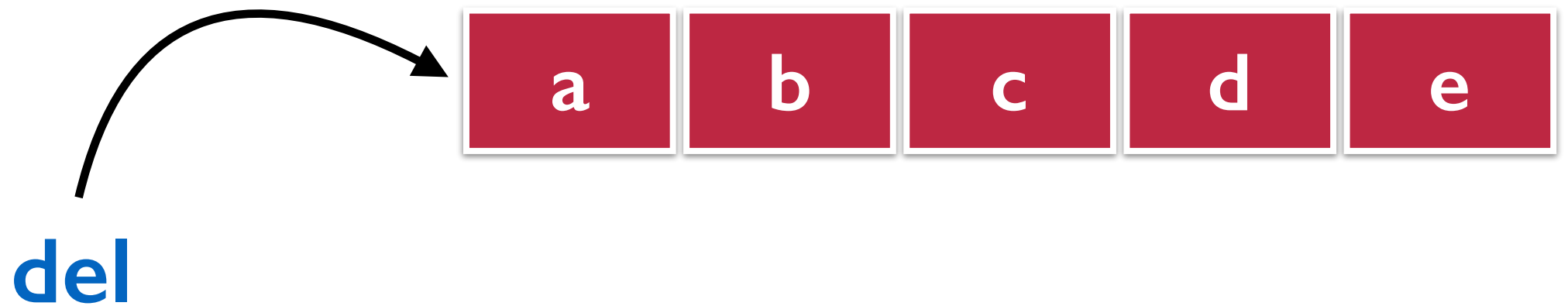
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Typing the Queue

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offers choice
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send element
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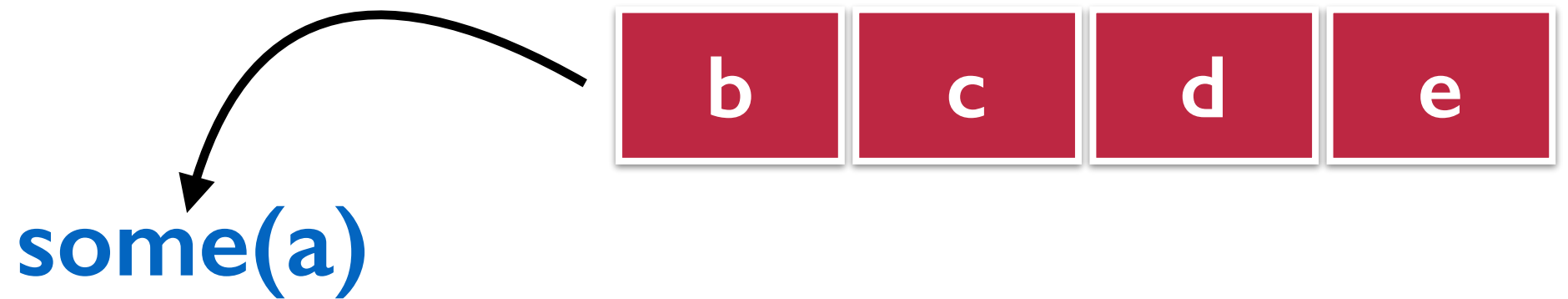
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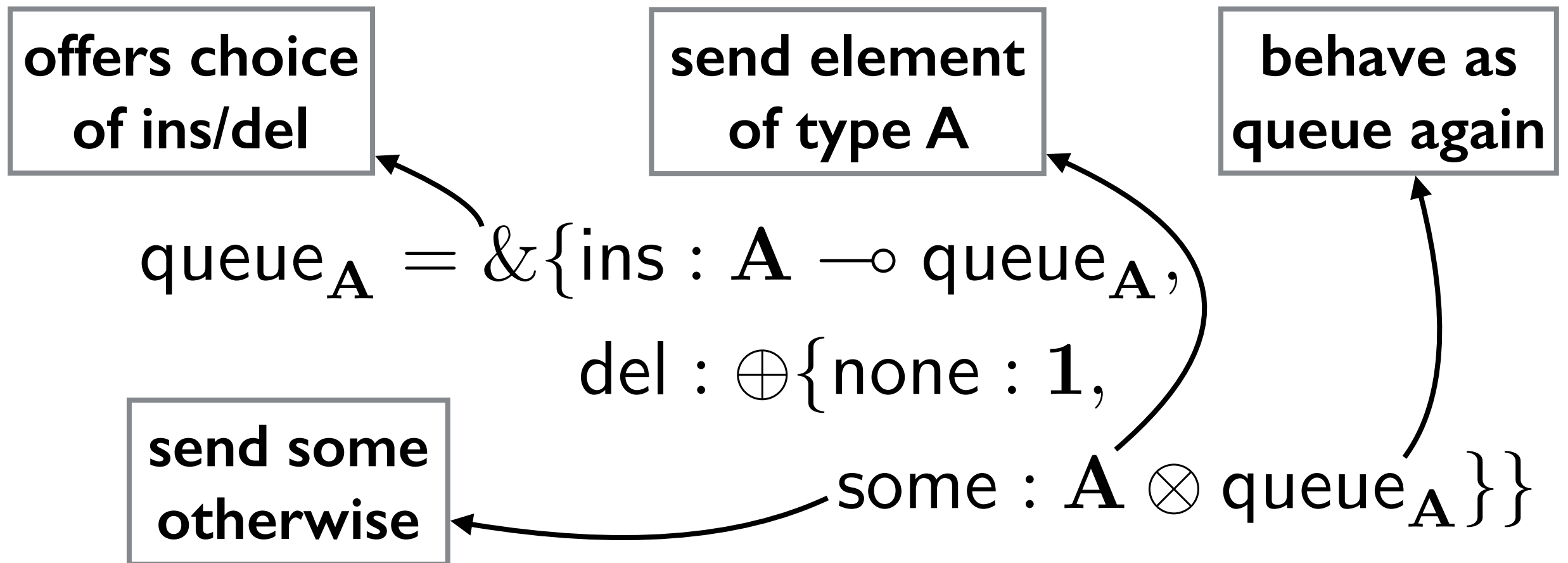
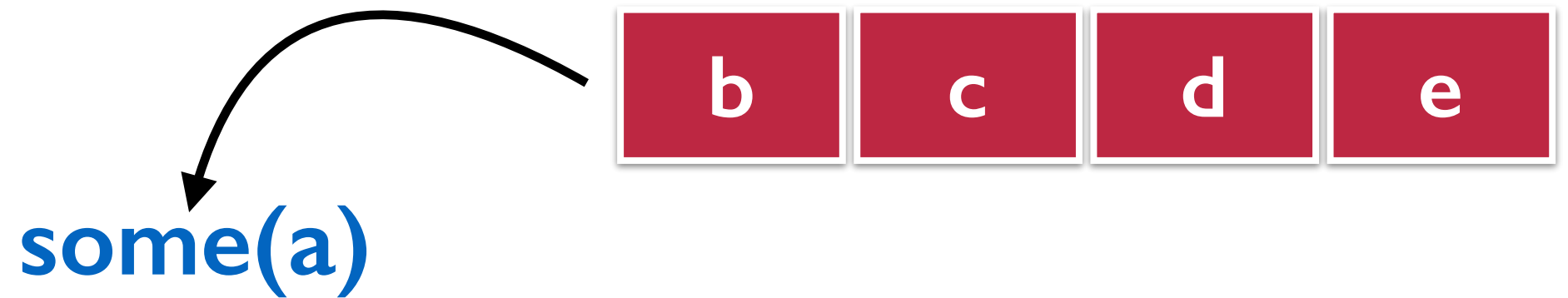
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Typing the Queue

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Response Time of Queues

19

$$\begin{aligned} \text{queue}_A = & \square \&\{\text{ins} : \bigcirc(\square A \multimap \bigcirc^3 \text{queue}_A)\}, \\ & \text{del} : \bigcirc \oplus \{\text{none} : \bigcirc 1, \\ & \quad \text{some} : \bigcirc(\square A \otimes \bigcirc \text{queue}_A)\}\} \end{aligned}$$

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Can always accept ins/del messages

Response Time of Queues

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Can always accept ins/del messages

Response time for insertion: 3

Response Time of Queues

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Can always accept ins/del messages

Response time for insertion: 3

Response time for deletion: 1

Response Time of Queues

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Can always accept ins/del messages

Response time for insertion: 3

Response time for deletion: 1

Precision

WE ARE
HERE!

Flexibility

Typing Rules(\square)

Typing Rules(\Box)

20

Exchanged token is a now! message

$$\frac{\Omega \text{ delayed}^{\Box} \quad \Omega \vdash P :: (x : S)}{\Omega \vdash \text{when? } x ; P :: (x : \Box S)} \Box R$$

$\text{delayed}^{\Box} = \bigcirc^* \Box T \rightarrow \text{can be delayed indefinitely}$

Typing Rules(\Box)

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$$\frac{\Omega, x : S \vdash Q :: (z : T)}{\Omega, x : \Box S \vdash \text{now! } x ; Q :: (z : T)} \Box L$$

Stacks vs Queues

21

RS cost model

$$\begin{aligned} \text{stack}_A = \square \, \& \{ \text{ins} : \bigcirc(\square A \multimap \bigcirc \text{stack}_A) \}, \\ & \text{del} : \bigcirc \oplus \{ \text{none} : \bigcirc 1, \\ & \quad \text{some} : \bigcirc(\square A \otimes \bigcirc \text{stack}_A) \} \} \end{aligned}$$

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Which one's more efficient?

Stacks vs Queues

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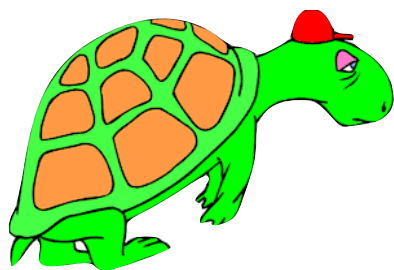
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Which one's more efficient?

Features of Type System

22

- ▶ **Parametric:** time can be defined using a cost model
- ▶ **Compositional:** types describe individual processes, not just whole programs
- ▶ **Precise & Flexible:** ○ operator provides precision.
□, ◇ operators provide flexibility
- ▶ **Conservative:** only added 3 type operators
- ▶ **General:** works on all standard examples
- ▶ **Automatic:** supports automatic type checking, type inference future work

$\text{proc}(c, t, P)$

**Process P offering along
channel c at local time t**

$\text{proc}(c, t, P)$

**Process P offering along
channel c at local time t**

Soundness Theorem:

**message timings realized by the local clocks
matches the timing predicted by the type system**

What else is in the paper?

24

- ▶ Interaction of \square , \diamond with \bigcirc operators
- ▶ Sound and complete *subtyping* relation
- ▶ *Time Reconstruction* — inserting *delay*, *now!*, *when?* automatically from the program type
- ▶ *Cost Semantics* — each process stores a *local clock*, expresses timing at runtime, connected to the type system by a proof of *progress* and *preservation*
- ▶ Connection to the standard cost semantics
- ▶ Typing a set of processes at *different* local clocks

Conclusion

Conclusion

25

Type System

analyzes timing of message exchanges

Soundness Theorem

Cost Semantics

local clocks at each process

Properties

conservative extension, added 3 type operators

○ provides precision, □, ◇ provide flexibility

Examples

throughput and latency of bit stream processors

response time of stacks vs queues

list examples: append, map, fold (many more in paper!)